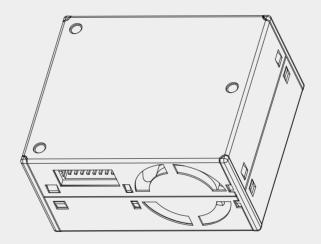


# MPM14-CS

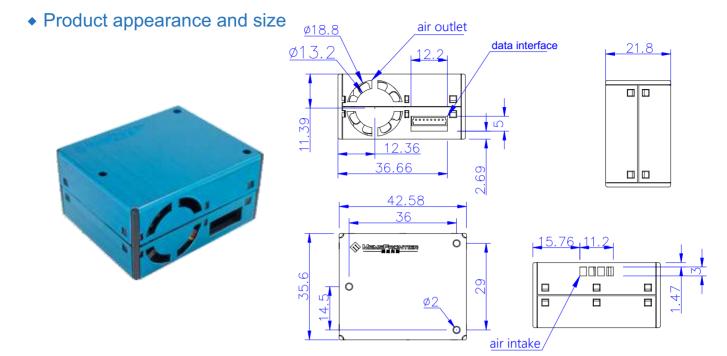
Air Laser Particulate Matter Sensor



# SPECIFICATION

Shenzhen MemsFrontier Electronics Co., Ltd.





# Product parameters

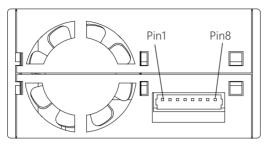
parameters	index	unit
Types of particle detection	PM1.0, PM2.5, PM10	
Particle detection diameter range	0.3-10	( µm )
Particulate matter concentration range (PM2.5 standard value)	0~1000	(µg/m3)
Particle Mass Concentration Resolution	1	(µg/m3)
Consistency of particulate matter concentration (PM2.5 standard value) *Note	±10%(@100~500μg/m3 ) ±10μg/m3 (@ 0~100μg/m3 )	
single response time	≤1	(s)
Comprehensive response time	≤10	(s)
DC supply voltage	Typ:5.0 Min:4.5 Max: 5.5	(V)
Working current	≤80	( mA )
Stand-by current	≤20	( mA )
output method	UART / IIC / PWM	
Data interface level	L < 0.8 (@3.3); H > 2.7(@3.3)	(V)
Storage temperature	- 30 ~ +70	( °C )
Range of working temperature	-10~+60	( °C )
Working humidity range	0~99%RH (no condensation)	
Mean time between failures	≥5	(Year)
Dimensions	42.58x35.6x21.8mm(L×W×H)	( mm )

Note: The particle concentration consistency data is data 2 in the communication protocol (test conditions: 25±2°C, 50±10%RH).

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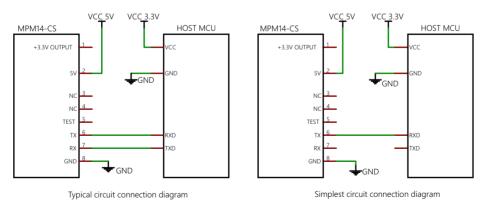
## Pin Diagram



Single row 8 PIN connector

Pin number	Pin name definition	Pin function description	Pin Electrical Characteristics		
Pin 1	+3.3V	3.3V/100mA output			
Pin 2	5V	+5V power input	No reverse polarity protection		
Pin 3	NC	Vacant			
Pin 4	NC	Vacant			
Pin 5	TEST	For testing (floating)			
Pin6	ТХ	UART TX output (0-3.3V)			
Pin7	RX	UART RX input (0-3.3V)			
Pin 8	GND	5V power ground			

### circuit connection



Circuit design should pay attention to:

1. The power supply voltage of the MPM14-CS module is 5V. The data communication and control pins are both 3.3V as high level, so the mainboard MCU connected to communicate should be powered by 3.3V. If the main board MCU is powered by 5V, a level conversion chip or circuit should be added to the communication line (RX, TX).

2. Attention should be paid when applying the hibernation function: the fan stops working during hibernation, and it takes at least 30 seconds to stabilize the fan to restart. Therefore, in order to obtain accurate data, the working time of the module after hibernation and waking up should not be less than 30 seconds.

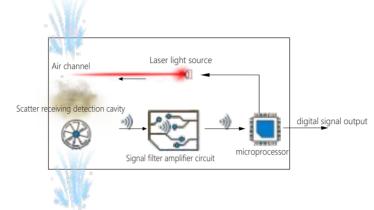


#### MPM14-CS

#### Air Laser Particulate Matter Sensor

#### working principle

According to the principle of laser scattering, the laser beam emitted by the laser irradiates the suspended particles in the air to generate scattering, and the laser photoelectric receiver is placed at a specific position to collect the scattered light, and the curve of the scattered light intensity with time is obtained. Microprocessing collects the electrical signal of the receiver in real time, and uses the algorithm based on Mie theory to obtain the equivalent particle size of the particles and the number of particles with different particle sizes per unit volume. The functional block diagram of the sensor is shown in the following figure.



### Serial communication protocol

Serial output is divided into two states: automatic output and passive output. After the module is powered on, the default state is automatic output, that is, the module actively sends serial data to the host, and the time interval is 1sec. The host MCU can send an instruction to turn the module into passive output mode, and the host MCU initiates a query command for passive output, and the module responds to output data once.

Default baud rate: 9600bps Check bit: none Stop bit: 1 bit, total data length: 32 bytes

Number	byte	Numerical value	Descriptions
0	start character 0	0x42	(fixed)
1	start character 1	0x4d	(fixed)
2	Frame length high byte	**	
3	frame length low byte	**	Frame length=2x13+2(data+check digit)
4	data O high byte	**	rocon /0
5	data O low byte	**	reserve
6	Data 1 high byte	**	
7	Data 1 low byte	**	PM2.5 concentration value (standard particulate matter), unit µg/m
8	Data 2 high byte	**	
9	Data 2 low byte	**	Pm10 concentration value (standard particulate matter), unit µg/m3*
10	Data 3 high byte	**	
11	Data 3 low byte	**	reserve
12	Data 4 high byte	**	
13	Data 4 low byte	**	reserve
14	Data 5 high byte **		
15	Data 5 low byte **		reserve
16	Data 6 high byte **		
17	17 Data 6 low byte		reserve

Serial port automatic output data format:



Air Laser Particulate Matter Sensor

Number	byte	Numerical value	Descriptions	
18	Data 7 high byte	**		
19	Data 7 low byte	**	reserve	
20	Data 8 high byte	**		
21	Data 8 low byte	**	reserve	
22	Data 9 high byte	**		
23	Data 9 low byte	**	reserve	
24	Data 10 high byte	**		
25	Data 10 low byte	**	reserve	
26	Data 11 high byte	**		
27	Data 11 low byte	**	reserve	
28	Data 12 high byte	**		
29	Data 12 low byte		- reserve	
30	Data and parity high byte	**		
31	Data and parity low byte	**	Check code = start symbol 1 + start symbol 2 + + data 12 low byte	

Note: The standard particle mass concentration value refers to the mass concentration value obtained by using industrial metal particles as equivalent particles for density conversion, which is suitable for industrial production workshops and other environments. The mass concentration value of particulate matter in the atmospheric environment is converted into the density of the main pollutants in the air as equivalent particles, which is suitable for ordinary indoor and outdoor atmospheric environments.

Communication protocol command function description and format description:

Instruction function description	frame header HEAD	length LEN	command CMD	DATA	check byte CS	Example
stop automatic sending	0x68	0x01	0x20	NA	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	68 01 20 77
normal response	I			0	xA5A5	
Response exception				0	x9696	
Enable automatic sending	0x68	0x01	0x40	NA	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	68 01 40 57
normal response	0xA5A5					
Response exception	0x9696					
Start measuring particle concentration	0x68	0x01	0x01	NA	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	68 01 01 96
normal response	0xA5A5					
Response exception		0x9696				



MPM14-CS Air Laser Particulate Matter Sensor

0x68	0x01	0x02	NA	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	68 01 02 95
	1		0xA	5A5	
			0x96	596	
0x68	0x01	0x04	NA	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	68 01 04 93
0x40	0x05	0x04	"Df1, DF2, DF3, DF4 PM2.5 = DF1 * 256 + DF2 PM10 = DF3 * 256 + DF4"	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	40 05 04 00 30 00 31 56
0x9696					
0x68	0x01	0x10	NA	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	68 01 02 95
0x40	0x02	0x10	Df1: 30 ~ 200 (Defalut:100)	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	40 02 10 64 4A
0x9696					
0x68	0x02	0x08	Df1: 30 ~ 200 (Default, 100)	CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)	68 02 08 64 2A
	0xA5A5				
	0x9696				
	0x68 0x40 0x68 0x40	0x68 0x01 0x40 0x05 0x68 0x01 0x68 0x01 0x40 0x02	0x68   0x01   0x04     0x40   0x05   0x04     0x68   0x01   0x10     0x68   0x01   0x10     0x68   0x01   0x10     0x68   0x02   0x10	NA     NA       0x68     0x01     0x04     NA       0x68     0x01     0x04     NA       0x40     0x05     0x04     "Df1, DF2, DF3, DF4 PM2.5 = DF1* 256 + DF2 PM10 = DF3 * 256 + DF4"       0x68     0x01     0x10     NA       0x68     0x01     0x10     Df1: 30 ~ 200 (Defalut:100)       0x68     0x02     0x10     Df1: 30 ~ 200 (Defalut:100)       0x68     0x02     0x08     Df1: 30 ~ 200 (Defalut:100)	0x68     0x01     0x02     NA     ((65536-(HEAD+LEN+CMD+DATA)), 256)       0x40     0x01     0x04     NA     CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)       0x40     0x05     0x04     "Df1, DF2, DF3, DF4 PM2.5 = DF1* 256 + DF2 PM10 = DF3*256 + DF4"     CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)       0x40     0x05     0x04     "Df1; 30 ~ 200 (Defalut:100)     CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)       0x68     0x01     0x10     NA     CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)       0x40     0x02     0x10     Df1: 30 ~ 200 (Defalut:100)     CS = MOD ((65536-(HEAD+LEN+CMD+DATA)), 256)       0x68     0x02     0x08     Df1: 30 ~ 200 (Defalut:100)     CS = MOD (G5536-(HEAD+LEN+CMD+DATA)), 256)       0x68     0x02     0x08     Df1: 30 ~ 200 (Default, 100)     CS = MOD (G5536-(HEAD+LEN+CMD+DATA)), 256)

### Installation Precautions

1. The metal shell of the module is connected to the internal power supply ground. Be careful not to short-circuit with other circuits or the chassis shell.

It is the best installation method that the plane where the air inlet and air outlet are located is close to the air hole on the inner wall of the user machine that communicates with the outside world. There should be a structure between the air inlet and the air outlet to isolate the airflow to prevent the airflow from directly flowing back from the air outlet to the air inlet inside the user machine.
The ventilation hole opened for the air inlet on the inner wall of the user machine should not be smaller than the size of the air inlet.
When applied to purifier products, try to avoid placing the module directly in the air duct of the purifier itself. If it is unavoidable, an independent structure space should be set up separately, and the module should be placed in it so that it is connected to the purifier itself. Air duct isolation.

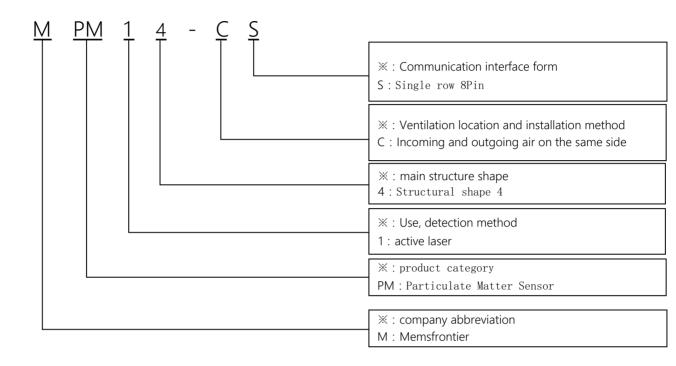
5. When applied to purifiers or fixed testing equipment, the module position should be more than 20cm above the ground. Otherwise, it may be polluted by large dust particles or even flocs near the ground, causing the fan to wind up and stop rotating.6. When the module is applied to outdoor fixed equipment, the protection against sandstorms, rain and snow, and willow catkins should be completed by the equipment.

7. The module is an integral component, users should not disassemble it, including the metal shielding case, to prevent irreversible damage.

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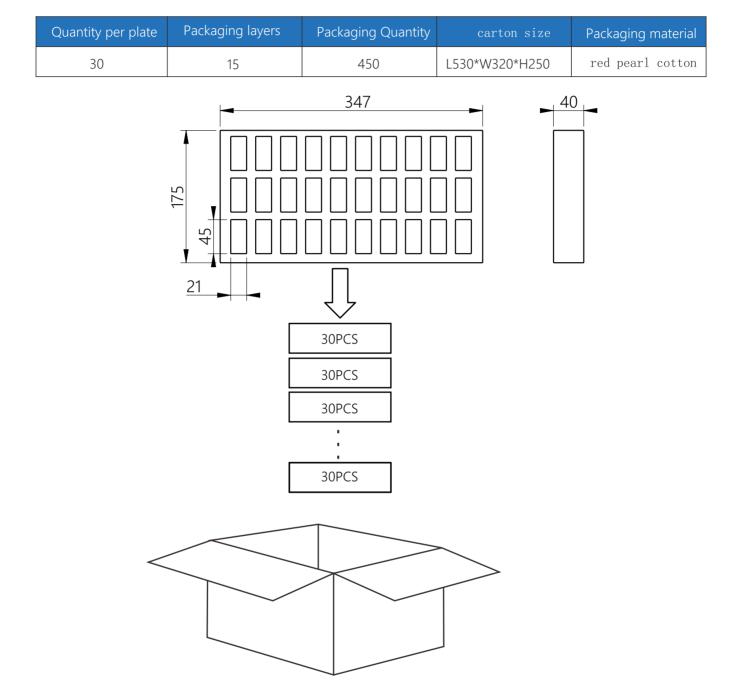


# Number Description





# Packing



• Version history

date	version	change
2022.3.5	1.00	initial version
2022.7.20	1.10	Add the description of the number and the category of the packaging method